Fault Flooding Migration Project

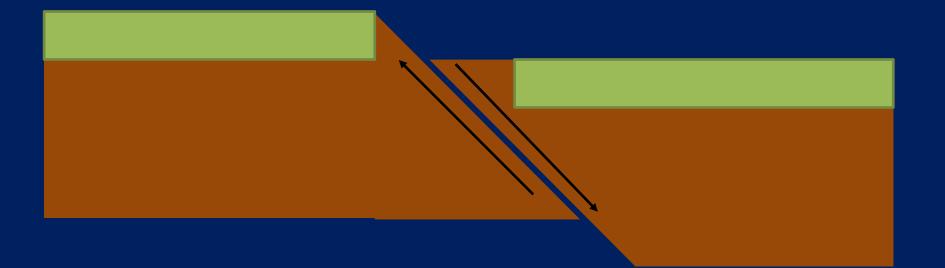
Ahmed Metwally Maximillian Kosmicki

Earth Science and Engineering Department (ErSE), King Abdullah University of Science and Technology (KAUST).

- Motivation: Finding Steeply Dipping Faults
- Theory: 'Fault Flooding' Method
- Workflow: Overview of Steps
- Synthetic Data Trial: Vertical Fault Example
- Gulf Of Aqaba Data: Field Data Results

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Motivation



To accurately obtain fault parameters using seismic data.

 Implications for Seismology and Civil/Geological Engineering

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The migration equation for imaging the fault is given by:

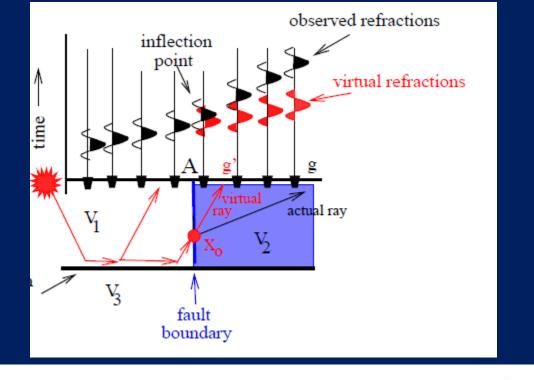
$$m(\mathbf{x}) = \sum_{\omega} \sum_{s} \sum_{g} \sum_{g'} \Phi(\mathbf{g}, \mathbf{g}', \mathbf{s}, \omega) e^{-i\omega(\tau_{xg}^2 - \tau_{xg'}^1)}.$$

This equation. is equivalent to interferometrically detecting the location of a point source (Schuster, 2009) at xo, except now the source is at the location of the fault boundary.

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Workflow

1. Identify and isolate the refraction events whose move out curve sharply bends at a common surface location for shot gathers with shots on one side of the fault.



$$D(\mathbf{g}, \mathbf{s}, \omega)_{obs} = e^{i\omega(\tau_{sx_o}^1 + \tau_{x_og}^2)}; \qquad D(\mathbf{g}', \mathbf{s}, \omega)_{virt} = e^{i\omega(\tau_{sx_o}^1 + \tau_{x_og'}^1)},$$

Workflow

2. Correlate the recorded and virtual traces to give the correlated data:

$$\Phi(\mathbf{g}, \mathbf{g}', \mathbf{s}, \omega) = D(\mathbf{g}, \mathbf{s}, \omega)_{obs} D(\mathbf{g}', \mathbf{s}, \omega)^*_{virt} = e^{i\omega(\tau^2_{x_og} - \tau^1_{x_og'})}.$$

3. Apply the migration kernel :

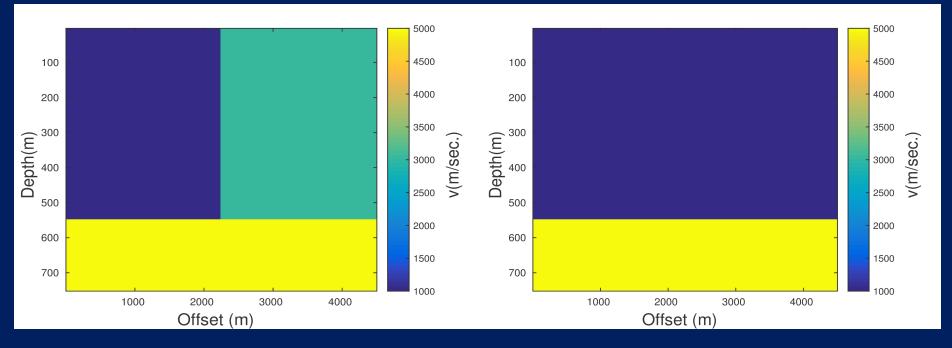
$$m(\mathbf{x}) = \sum_{\omega} \sum_{s} \sum_{g} \sum_{g'} \Phi(\mathbf{g}, \mathbf{g}', \mathbf{s}, \omega) e^{-i\omega(\tau_{xg}^2 - \tau_{xg'}^1)}.$$

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 Generate the synthetic data from the true velocity model and the 'fault flooded' virtual velocity model.

True velocity model

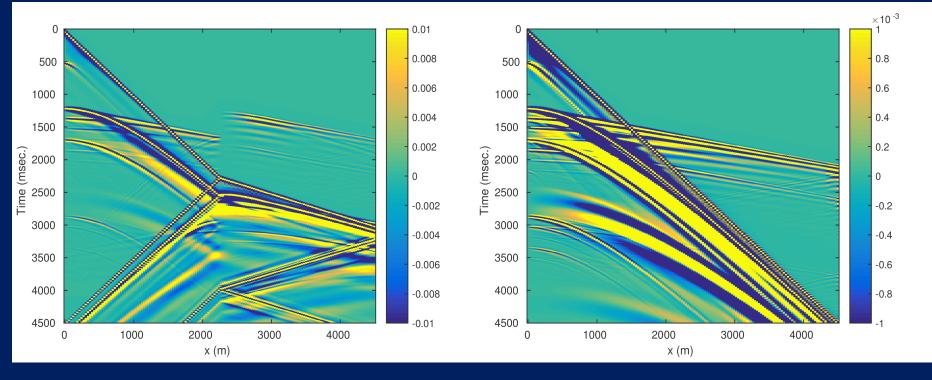
Virtual velocity model



2. Identify and isolate the refraction events in the datasets.

Observed data

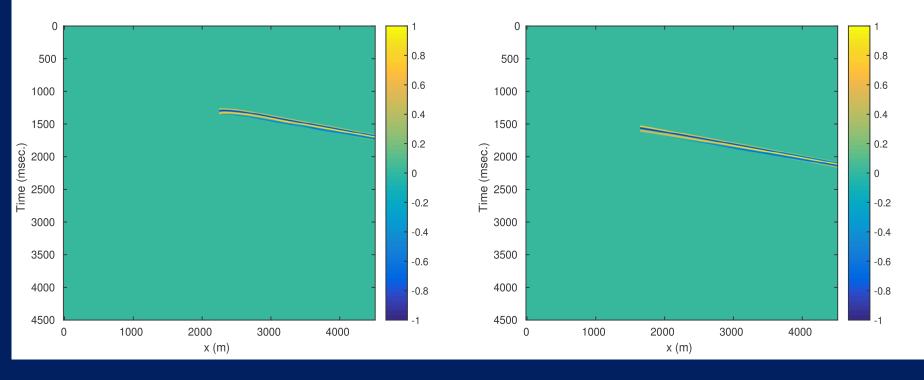
Virtual data



2. Identify and isolate the refraction events in the datasets.

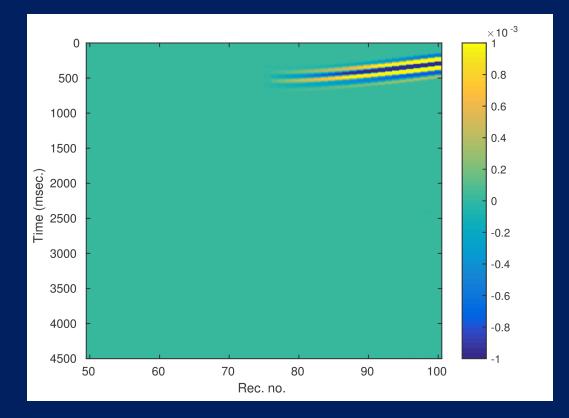
Refractions only from observed data

Refractions only from Virtual data



3. Correlate the recorded (observed) and virtual traces to give the correlated data.

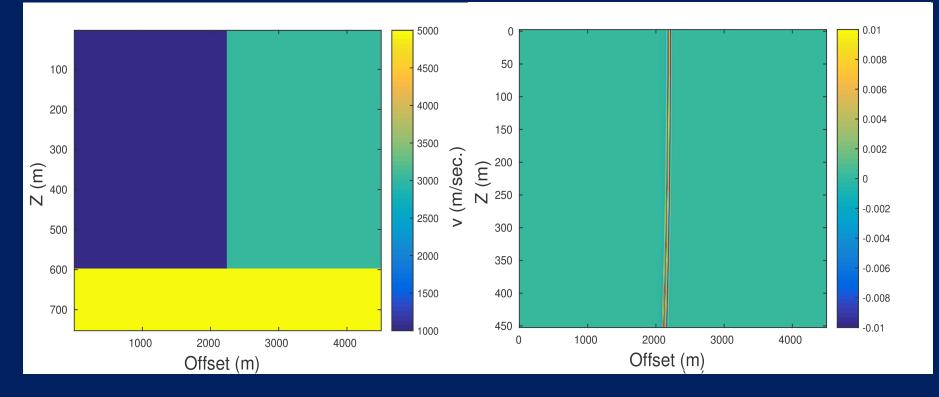
Cross Correlated Data



4. Apply the migration kernel to the cross correlated data.

True velocity model

Migration image for the fault

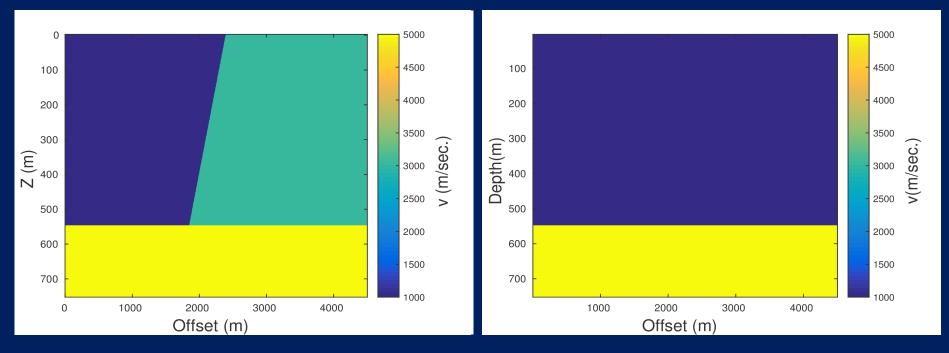


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True velocity model

Virtual velocity model



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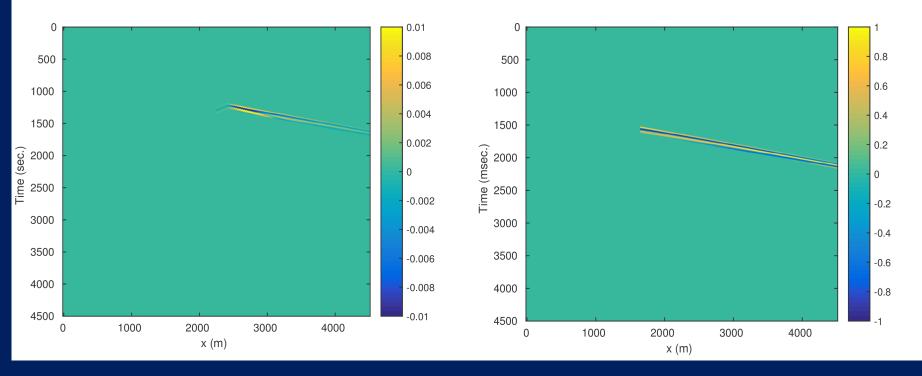
 $\times 10^{-3}$ $\times\,10^{-3}$ 0 0 0.8 0.8 500 500 0.6 0.6 1000 1000 0.4 0.4 1500 1500 0.2 0.2 Time (msec.) Time (sec.) 2000 2000 0 0 2500 2500 -0.2 -0.2 3000 3000 -0.4 -0.4 3500 3500 -0.6 -0.6 4000 -0.8 4000 -0.8 4500 4500 1000 2000 3000 4000 0 3000 4000 0 1000 2000 x (m) x (m)

Virtual data

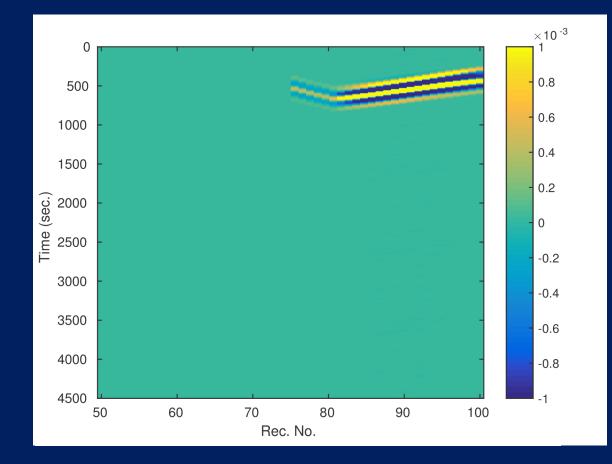
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Refractions only from observed data

Refractions only from Virtual data



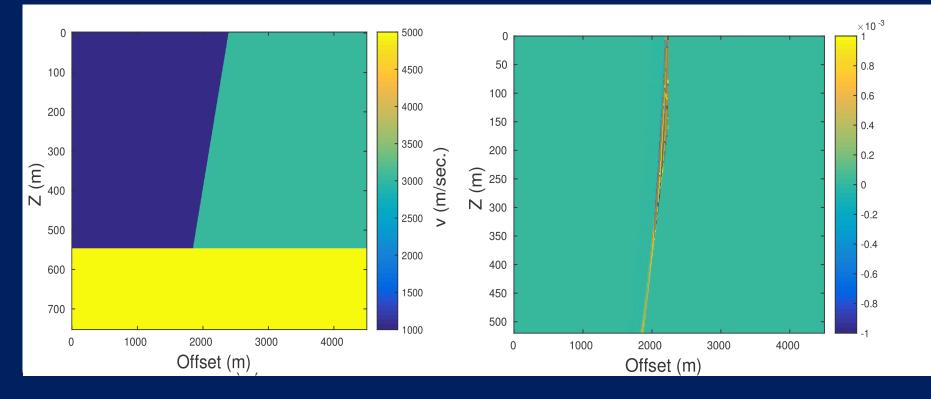
3. Correlate the recorded (observed) and virtual traces to give the correlated data.



4. Apply the migration kernel to the cross correlated data.

True velocity model

Migration image for the fault

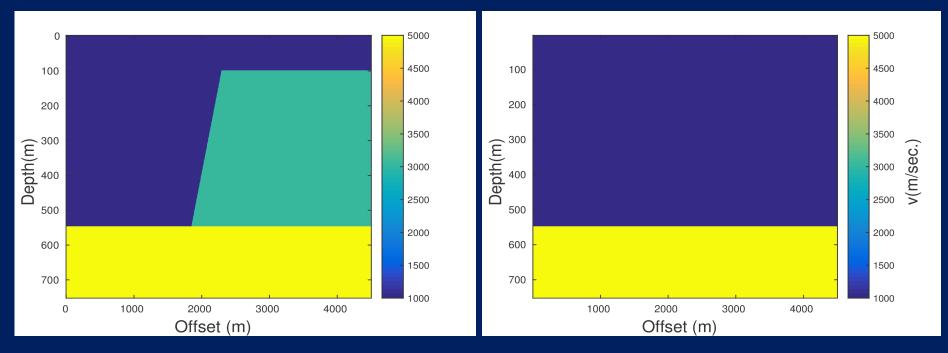


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True velocity model

Virtual velocity model



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Observed data

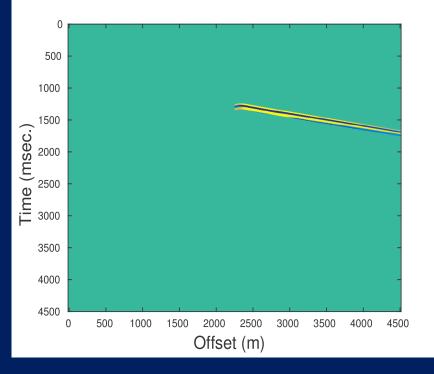
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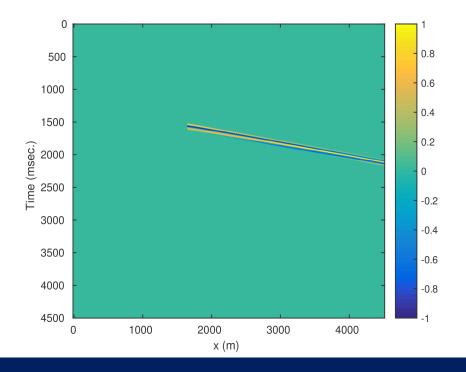
Virtual data

2. Identify and isolate the refraction events in the datasets.

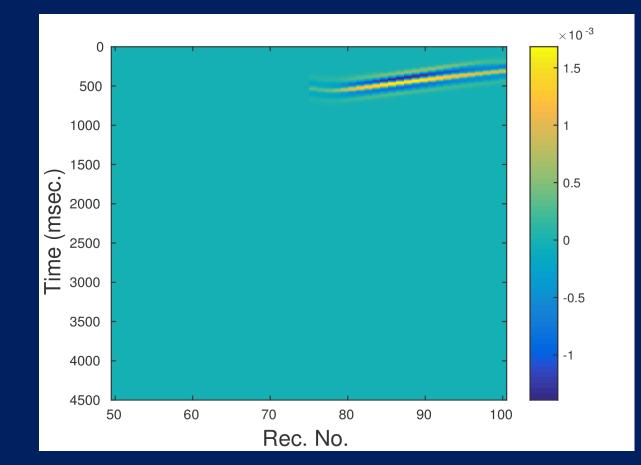
Refractions only from observed data

Refractions only from Virtual data





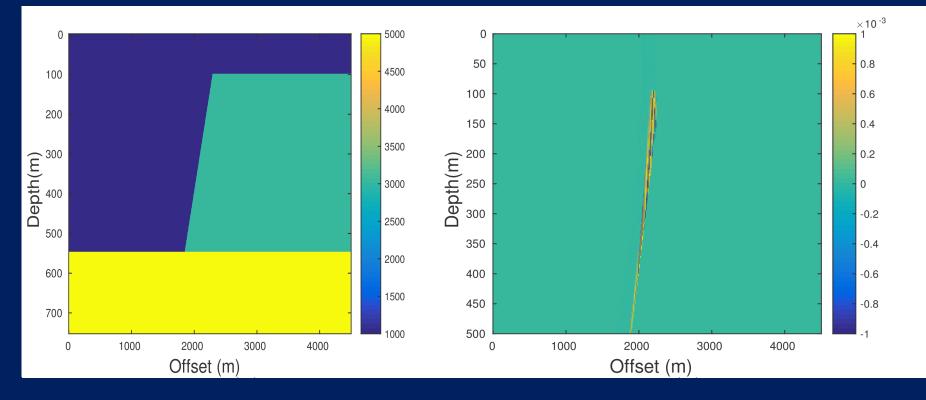
3. Correlate the recorded (observed) and virtual traces to give the correlated data.



4. Apply the migration kernel to the cross correlated data.

True velocity model

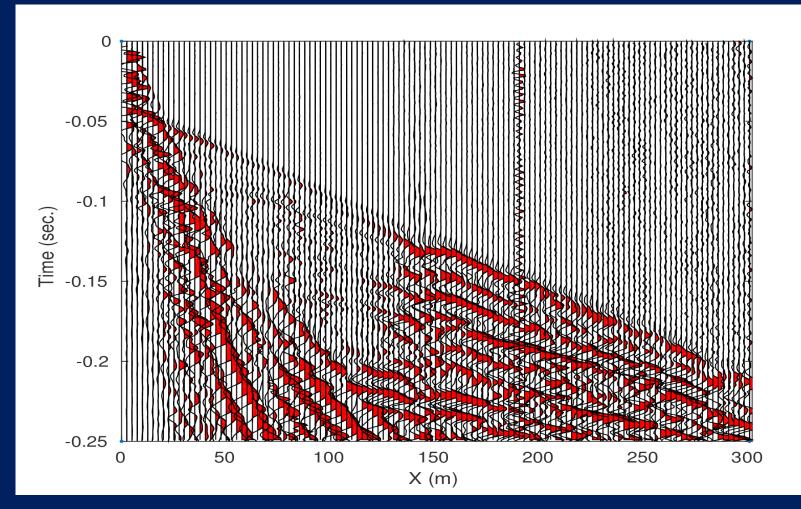
Migration image for the fault



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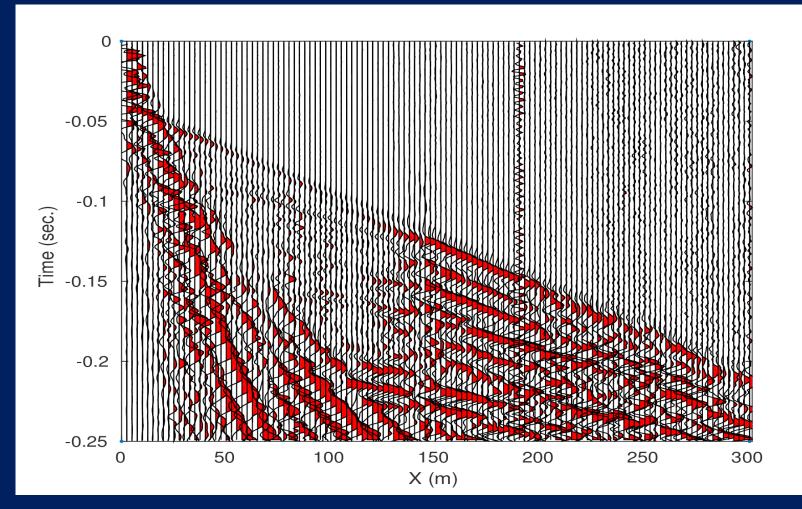
1. Manipulate real data to give the virtual refraction arrivals

Recorded data from the field



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Virtual Data from Shifting Events



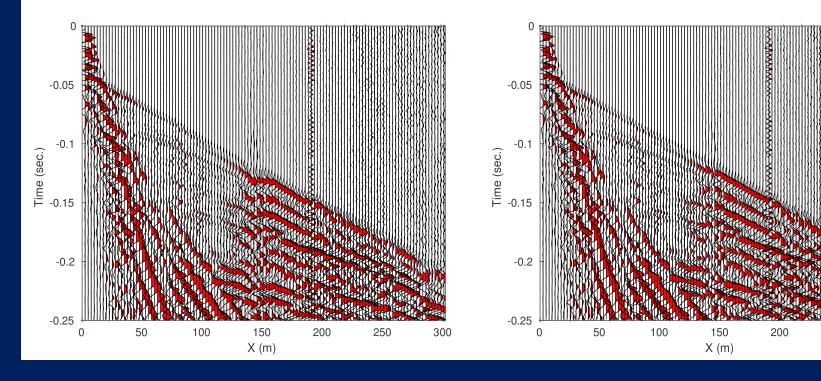
2. Identify and isolate the refraction events.

Observed data

Virtual data

250

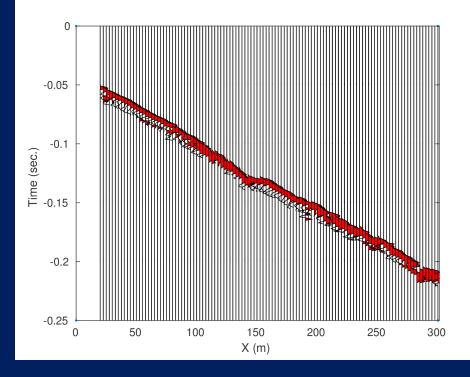
300

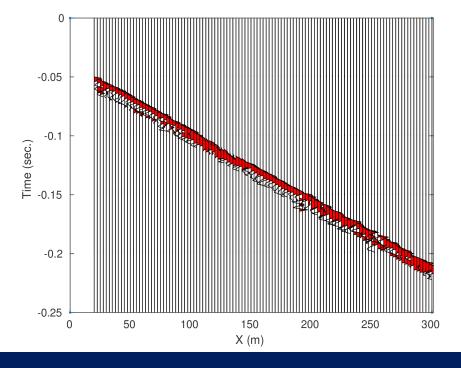


2. Identify and isolate the refraction events.

Refractions from Observed Data

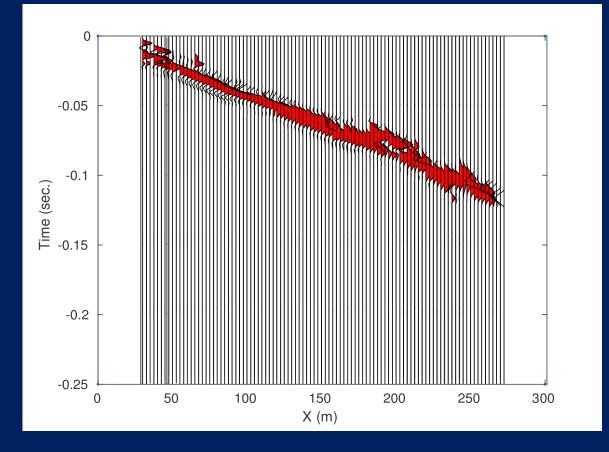
Refractions from Virtual data



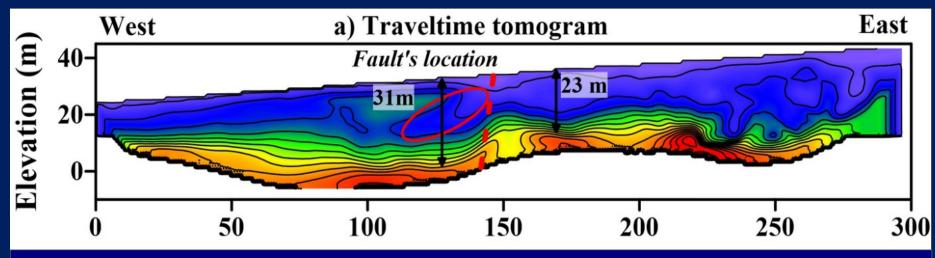


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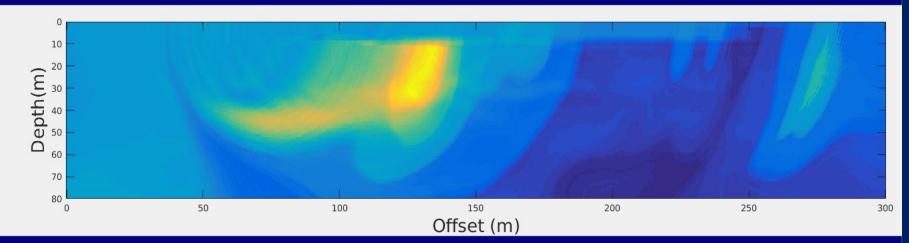
Cross Correlated data



Gulf of Aqaba Field Data 4. Apply the migration kernel.

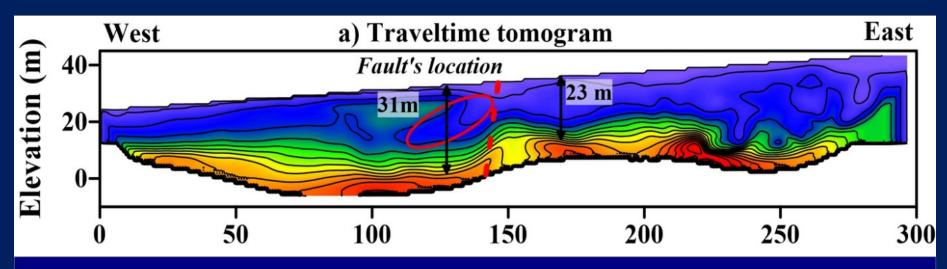


True velocity model

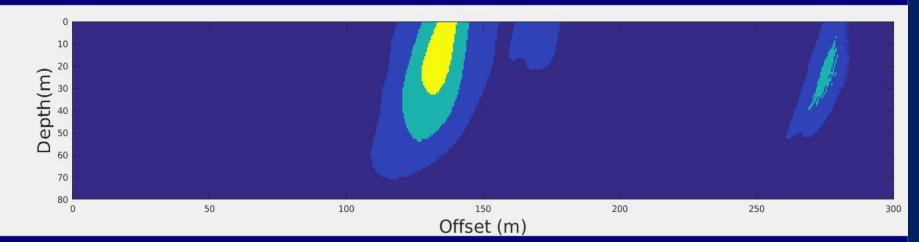


Migration image for the fault

Gulf of Aqaba Field Data 4. Apply the migration kernel.



True velocity model



Migration image for the fault

Limitations

 Need strong velocity contrast on either side of the fault scarp, strike slip faults could not be accurately imaged.

 Possible to misidentify incoming refractions from deeper layers as faulting events.

Conclusions

- •The fault flooding method offers a new tool in analyzing the extents of near surface faults.
- Overcomes traditional weaknesses inherent in seismic imaging with imaging steeply dipping events.

References

- Schuster, G., 2009, Seismic Interferometry: Cambridge Press.
- Schuster, G., 2015, Imaging of Near-Surface Faults by Fault Flooding and Refraction Migration.
- Sherif M. Hanafy, SEG 2014, Imaging Normal Faults in Alluvial Fans using Geophysical Techniques: Field Example from the Coast of Gulf of Aqaba, Saudi Arabia.

Questions ? Thank you